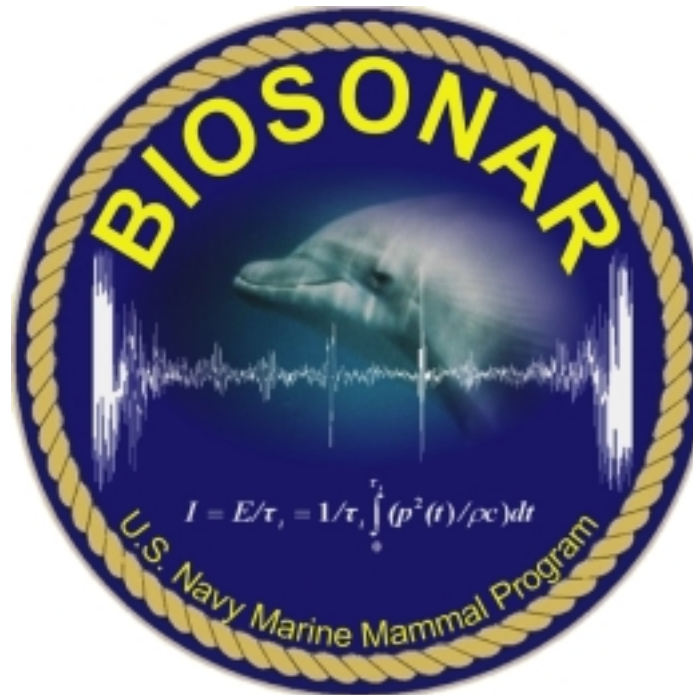


BIOSONAR



PROGRAM

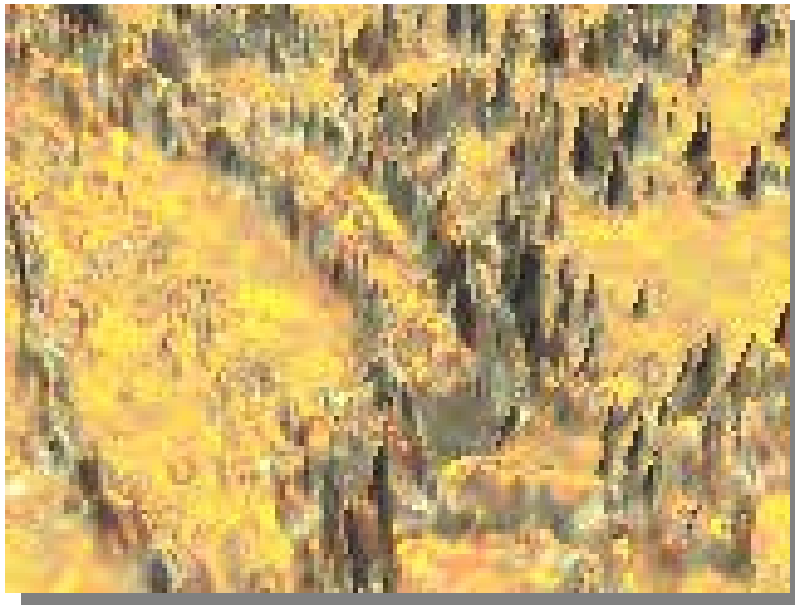
**Hardware Implementation
&
Evaluation of Dolphin-based Biosonar
Minehunting Principles**

**DARPA DSO
Dr. Alan S. Rudolph
Controlled Biological and Biomimetic Systems**

Biomorphic Explorers

Biomorphic Communication & Navigation

- Includes novel techniques inspired by bees, bats, **dolphins**, etc.



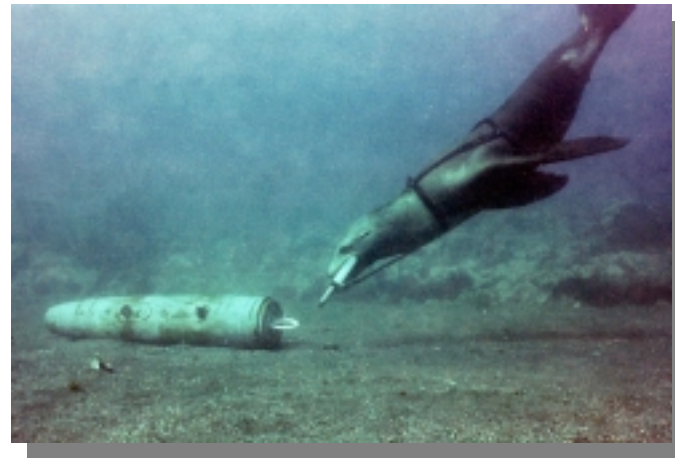
Mariana Trench

The ocean; Inner space-
A vast part of our planet that remains virtually unexplored due to its harsh and uninviting environment.

Marine Mammal Program



- Started in 1959
- Early research resulted in demonstrations of capabilities not available with hardware
- MMS systems developed and turned over to the Navy – MK 4, MK 5, MK 6 & MK7



SYSTEMS VIDEO

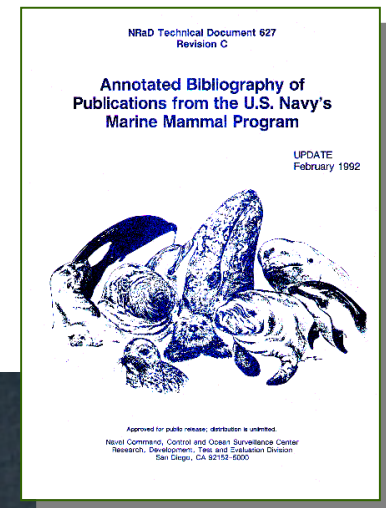
Marine Mammal Program



- **30 years of R & D**
 - ◆ Initial efforts centered on capabilities
 - ◆ Organized /co-organized 6 international meetings on animal biosonar
 - ◆ Over 900 publications
- **1984 Artificial Intelligence & bionics workshop, Stowe Vermont**

BIOSONAR MEETINGS

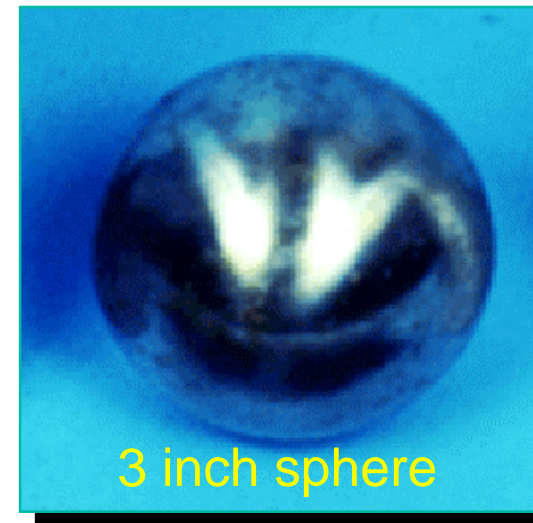
- 1996 – Frascati, Italy
- 1979 – Jersey, Jersey Isles
- 1986 – Helsingor, Denmark
- 1991 – Moscow, Russia
- 1995 – SPAWARSYSCEN
- 1998 – Carvoeiro, Portugal



DOLPHIN PERFORMANCE



- **DETECT 3" STAINLESS STEEL WATER-FILLED SPHERE AT 119m (-28dBTS)**
- **DETECT 0.2 mm WALL THICKNESS OF ALUMINUM CYLINDERS**
- **DISCRIMINATE MATERIAL**
 - ◆ ALUMINUM
 - ◆ GLASS
 - ◆ ROCK
 - ◆ BRASS
- **DISCRIMINATE SHAPE**
- **CLASSIFY TARGETS INDEPENDENT OF ASPECT**
- **DEMONSTRATE COGNITIVE SKILLS**



Biosonar Program Goals / Objectives



- Develop a biomimetic sonar that approaches the performance of MMS
 - ◆ Metrics - P_D , P_{FA} , P_{CC} & search rate
- Identify transition partner(s) for littoral applications in operational community
 - ◆ PMS-EOD-3 VSW MCM autonomous underwater vehicle program
 - ◆ Biomimetic / robotic platforms
 - ◆ PEO USW - ASTO (submarine active sonar)

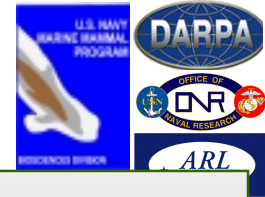
DBS Sonar System



- Two components: wet-end & dry-end
- ARL UT developing wet-end sonar set
- SSC SD developing dry-end & u/w trolley
- Sea tests at SSC SD
- SSC SD conduct algorithm assessments



Experiments



- **ALTER Binaural Models (stationary)**

- ◆ targets - simulators, distracters
- ◆ target position and substrate fixed & known
- ◆ grazing angle, depth, aspect, # of pings, range fixed & known
- ◆ actual dolphin received echoes

- **BMT Dolphin Benchmark (moving)**

- ◆ **Target Position and Substrate Known**
- ◆ **Waveform, Grazing Angle, Depth, Range, and Speed Selected by Dolphin, Quantified by BMT (Search Pattern)**
- ◆ **Dolphin Received Echoes**

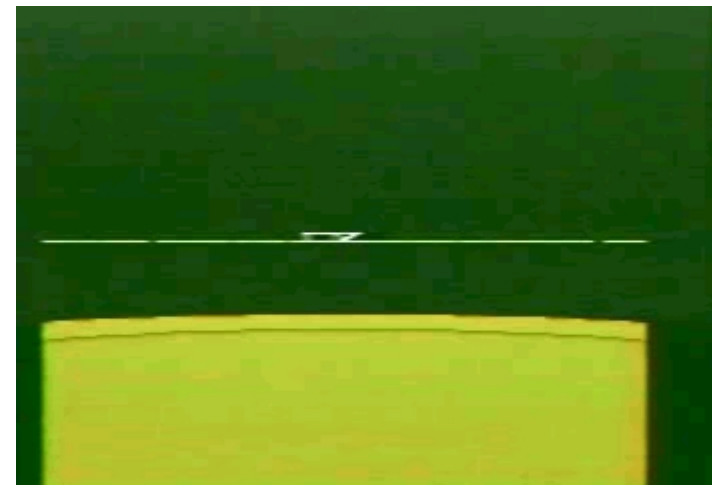
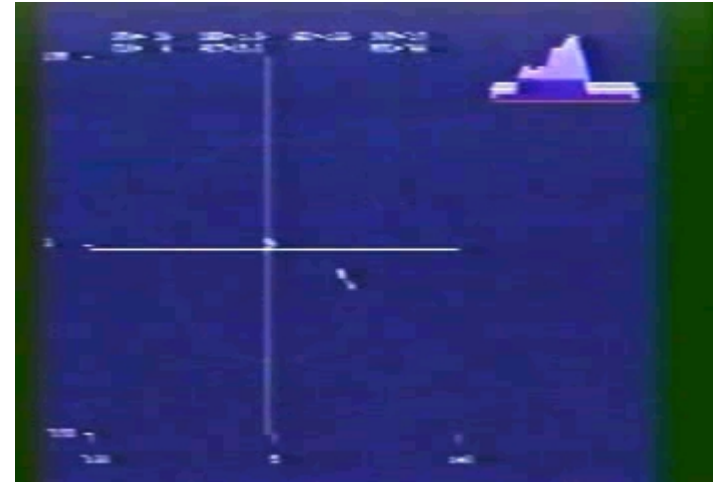
- **DBS Biosonar (moving)**

- ◆ controlled testing of hypotheses from above & brassboard implementation
- ◆ target position and substrate known
- ◆ waveform, grazing angle, depth, range, and speed selected by sonar operator (research team)
- ◆ comparison with dolphin on same minefields

Acoustic Response Monitor ARM



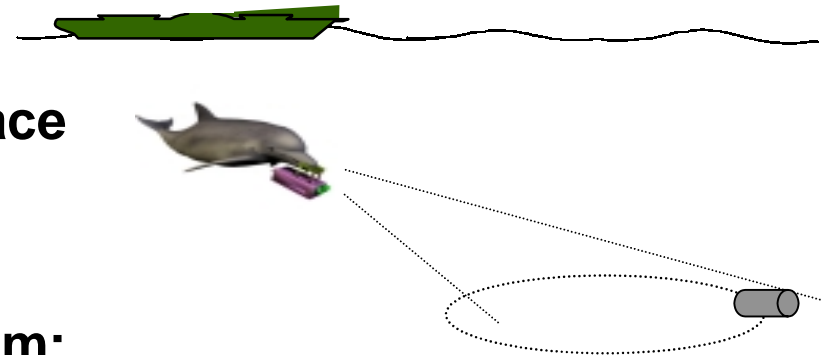
- First attempt to collect dynamic data
- Collected emitted signals for source analysis
- Required animal to remain at boat station
- Provided initial insight to signal modification



Biosonar Measurement Tool Concept



- Instrumented Open ocean dolphin performing actual MCM task
 - ◆ 20 ft. work boat with dolphin transport capability, DGPS surface nav., swim buoy, targets, onboard data upload computer
 - ◆ Bite-plate data acquisition system: emitted signal, biomimetic binaural receiver, dolphin head orientation & motion dynamics
- Laboratory analysis of dolphin strategy & data for Detect - Classify algorithms using VRML



BMT Approach

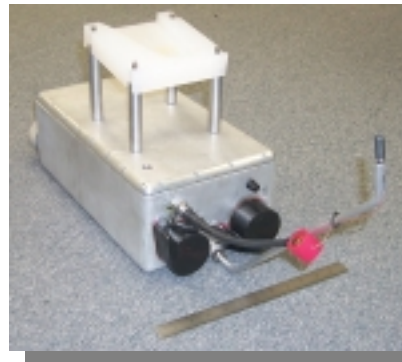


- FY99: Design, develop, validate new data collection package
 - ◆ Omni-directional outgoing biosonar click monitor hydrophone
 - ◆ Two directional hydrophones - model dolphins receiver
 - ◆ Underwater navigation system - passive inertial sensors (9DOF) and depth sensor.
 - > X,Y,Z magnetic/acceleration/angular rates
 - > Computed Heading, Pitch, Roll
 - > Independent depth sensor
- Workboat DGPS/Computer system
- Instrumentation validation in laboratory

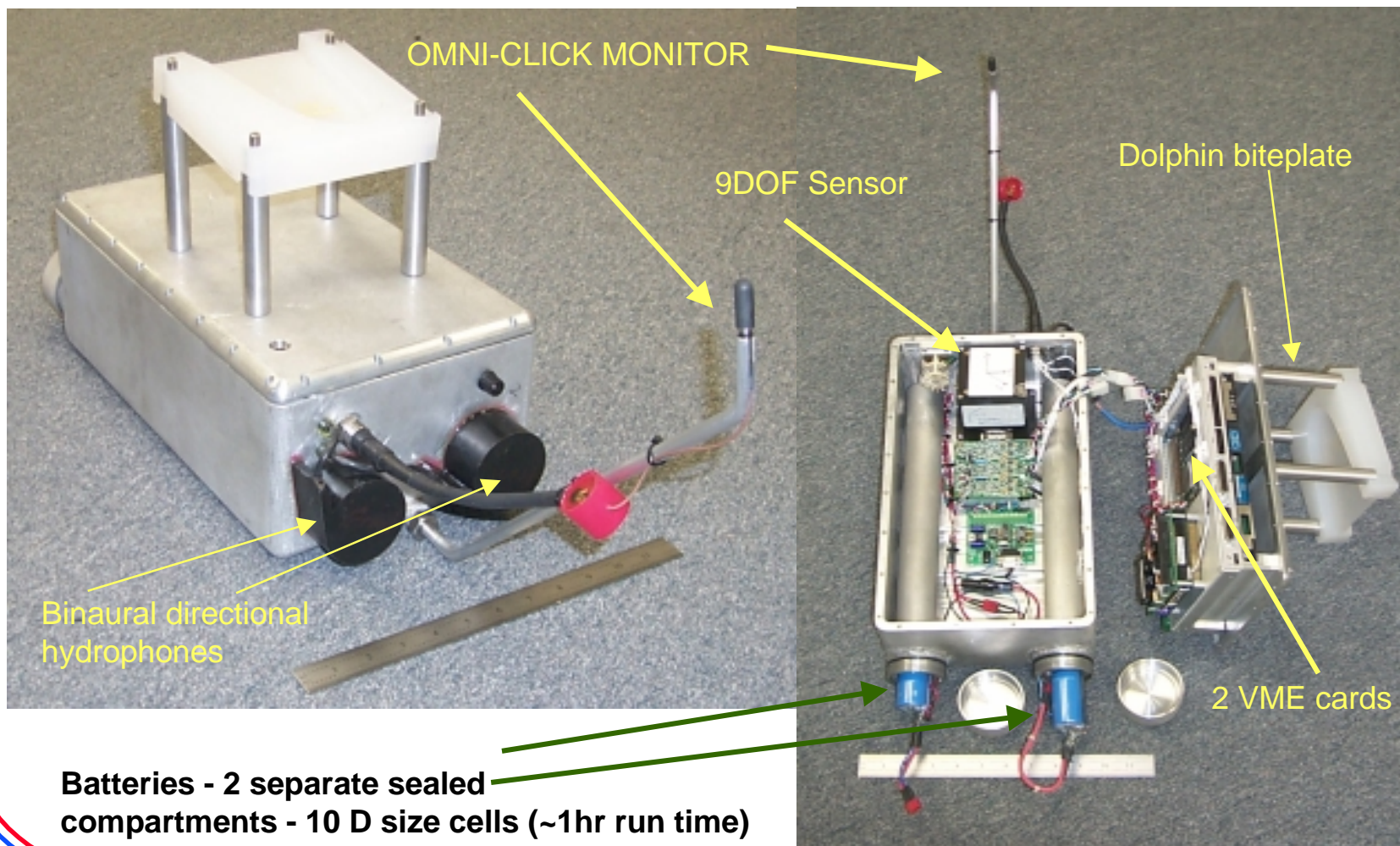
Biosonar Measurement Tool Overall Status



- Two Dolphins are trained to carry biteplate BMT - whistle when mine target detected.
- Boat DGPS/computer unit developed & installed
- Biteplate package operational in u/w housing



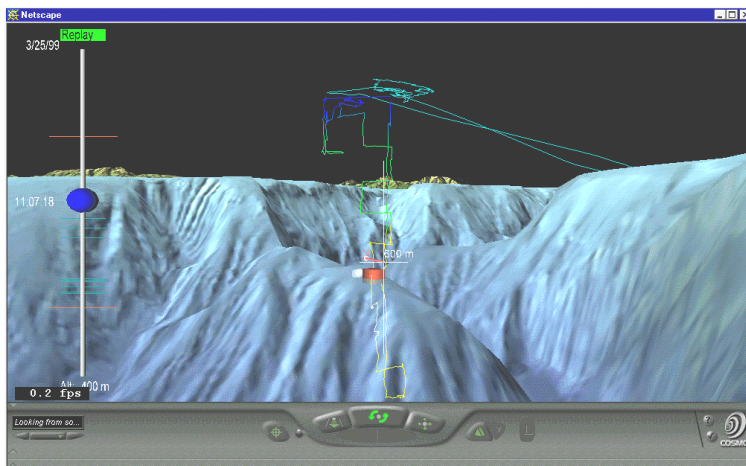
BMT in U/W Pressure Housing



Scientific Visualization



- Crucial to understand massive amounts of data as collect in this type of system
- Quickly review data runs, home in on interesting parts for detailed analysis
- Migrating to VRML / cooperation with Monterey Bay Aquarium Research Institute



BMT FOLLOW ON FY01



- **Analysis of Dolphin Biosonar minehunting strategies for buried targets**
 - ◆ Instrument mine shapes
 - ◆ BMT mods - smaller, lower power, active acoustic navigation
 - ◆ Automate simulation/playback - VRML
- **DARPA Biosonar Program**
 - ◆ 2 dolphins currently trained with BMT device
 - ◆ 1-2 more dolphins to be trained
 - ◆ In-pen data collection begun & open ocean experiments with dolphins should begin in weeks.

Summary



- Dolphin Based Sonar:
 - ◆ Truly broad band (BW > 80 kHz)
 - ◆ Biomimetic
 - ◆ Performance evaluated using Fleet metrics
 - ◆ Performance compared to Fleet assets
- Technology will produce significant advancement in Science and Technology domains
 - ◆ Littoral MCM
 - ◆ Broad band signal processing
 - ◆ Greater understanding of MMS
 - ◆ Biosonar capabilities